

# Handheld laser scanning for everyone

If you're looking for a fast and reliable way to map and understand spaces, meet the ZEB Go

### **Technical specification**

Range	30m (features <15m)
Laser	Class 1 / λ 905nm
FOV	360° x 270°
Protection class	IP 64
Processing	Post processing
Data logger carrier	Backpack
Scanner weight	850g
Colourised point cloud	<b>√</b> *
Referenced imagery	✓*
Scanner points per second	43,000
No. of sensors	1
Relative accuracy	1 - 3cm**
Raw data file size	100MB/min

#### **GeoSLAM Hub**

Transform your 3D scan data into actionable information

Automatic registration of multiple scans and geo-referencing

Import and manipulate data from any GeoSLAM device

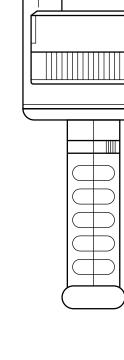
Quick & easy workflows with 'drag and drop' functionality

Optional Draw packages - Start, Plan, BIM, Mining and Pro

### **Accessories**

Pole - Elevate your device into ceiling voids		
Cradle - Lower your device into shafts		
<b>ZEB Pano</b> - 360° panoramic imagery		
<b>ZEB Cam</b> - Colourise your point cloud		

\*with ZEB Cam







<sup>\*\*</sup>environment dependent



# Handheld laser scanning for everyone

If you're looking for a fast and reliable way to map and understand spaces in real time, meet the ZEB Go RT

### **Technical specification**

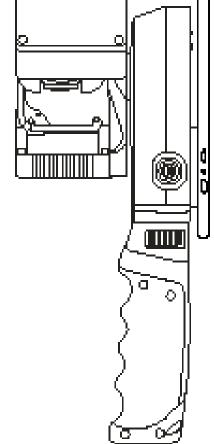
Range	30m (features <15m)
Laser	Class 1 / $\lambda$ 905nm
FOV	360° x 270°
Protection class	IP 51
Processing	Real time
Data logger carrier	Shoulder strap
Scanner weight	850g
Colourised point cloud	<b>√</b> *
Referenced imagery	<b>√</b> *
Scanner points per second	43,000
No. of sensors	1
Relative accuracy	1 - 3cm**
Raw data file size	100MB/min

### GeoSLAM Hub

Transform your 3D scan data into actionable information
Automatic registration of multiple scans and geo-referencing
Import and manipulate data from any GeoSLAM device
Quick & easy workflows with 'drag and drop' functionality
Optional Draw packages - Start, Plan, BIM, Mining and Pro

#### **Accessories**

Pole - Elevate your device into ceiling voids		
Cradle - Lower your device into shafts		
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\*with ZEB Cam

<sup>\*\*</sup>environment dependent



